

PERSONAL INFORMATION

Gani BALBAYEV

📍 Almaty, Kazakhstan

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Sex: Male | Date of birth: 11/04/1979

PREFERRED JOB

Associate Professor/Researcher

RESEARCH INTERESTS

Robotics, Mechatronics, Exoskeleton Design, Transmissions, Gearboxes, AI, Machine Learning, Aerospace Engineering

WORK EXPERIENCE

08/2021- to present

Vice-rector for science and cooperation, Academy of Logistics and Transport

04/01/2018 – 08/2021

Director of the Institute of Space Engineering and Telecommunications. Almaty University of Power Engineering and Telecommunications, Kazakhstan.

29/06/2017 – 03/01/2018

Head of Department of Electronics & Robotics. Almaty University of Power Engineering and Telecommunications, Kazakhstan.

10/10/2016 – 28/06/2017

Head of Department of Space Techniques and Technologies. Aerospace and Information Technologies faculty/ Almaty University of Power Engineering and Telecommunications, Kazakhstan

01/08/2016 – 10/10/2016

Vice Dean

Faculty of Radio Engineering and Telecommunications. Almaty University of Power Engineering and Telecommunications, Kazakhstan.

01/01/2016 – 01/08/2016

Associate Professor

Aerospace and Information Technologies faculty/ Dpt. of Electronics. Almaty University of Power Engineering and Telecommunications, Kazakhstan.

01/09/2015 – 01/01/2016

Senior Lecturer

Aerospace and Information Technologies faculty/ Dpt. of Electronics. Almaty University of Power Engineering and Telecommunications, Kazakhstan.

EDUCATION AND TRAINING

2012 – 2015

PhD in Mechanical Engineering
University of Cassino and South Latium, Cassino, Italy
(with support of grant “BOLASHAK”)

1996 – 2001

Basic education – Mechanical Engineering
Kazakh National Technical University, Almaty, Kazakhstan.

01/07/2015 – 01/08/2015

FELLOWSHIP. Short term training at LARM: Laboratory of Robotics and Mechatronics

University of Cassino and South Latium, Cassino, Italy

20/01/2011 – 22/03/2011

Scholarship of MIA of India, ITEC programme, “Graphic designing” at APTECH Ltd. Delhi, India.

SKILLS AND COMPETENCES

- Computer Skills SolidWorks, AutoCAD, GIM, MSC Adams, LabView, Python
- Languages English – C1, Russian – C2, Kazakh – C2

RESEARCH ROJECTS

2014 - 2017

1. Grant funding of the Ministry of Education and Science of the Republic of Kazakhstan, title “Development of adaptive drives for manipulators”, **Investigator**. Period: 36 months, at Institute of Mechanics and Machines after academician Dzoldasbekov U.

2018 - 2020

2. Grant funding of the Ministry of Education and Science of the Republic of Kazakhstan, for the project "Research and development of an innovative LED power source", **Supervisor of the project**. Period: 36 months, "Gylym Ordasy".

2018 - 2020

3. Grant of the Ministry of Education and Science of the Republic of Kazakhstan, for the project “Development and research of artificial vision of robotic systems”, **Main Investigator**. Period: 36 months, "Gylym Ordasy"

• International projects
2016 - 2019

1. Project under the program ERASMUS +, "InnoCENS Innovative competencies and entrepreneurial skills in higher technical education", **participant**. Period: 36 months, Almaty University of Power Engineering and Communications.

2016 - 2019

2. Project under the program ERASMUS +, "APPLE Applied curriculum on the development of outer space and intelligent robotic systems", **participant**. Period: 36 months, Almaty University of Power Engineering and Communications.

2020 - 2022

3. Project under the program ERASMUS +, "Acesyri Advanced Centre For Phd Students And Young Researchers In Informatics ", **Supervisor**. Period: 36 months, Almaty University of Power Engineering and Communications.

PUBLICATIONS

More than
40
publications
H-index 4

1. Nursultan, Z., Titov, A., Ceccarelli, M., **Balbayev, G.**, Design and Performance of a Motion-Assisting Device for Ankle. *Mechanisms and Machine Science* 113 MMS, c. 659-668.

2. **Balbayev, G.**, Mussina, A., Zhauyt, A., Shingissov, B., Kalekeyeva, M., Neural Control for Image Stabilisation Using a Reference Model. *International Journal of Mechanical Engineering and Robotics Research* 10(1), c. 17-21.

3. **G. Balbayev**, A. Nussibaliyeva, B. Tultaev, E. Dzhunusbekov, G. Yestemessova, A. Yelemanova. A novel regenerative snubber circuit for flyback topology converters. *Journal of Vibroengineering*. Vol. 22, Issue 4, 2020, p. 983-992. <https://doi.org/10.21595/jve.2020.20898>.

4. Ivanov, K., Ceccarelli, M., Yestemessova, G., Nurgizat, Y., Balbayev, G., Design and Characterization of a Gearbox Joint for Manipulators. *Mechanisms and Machine Science* 73, c. 2261-2268.

5. E. Nurgizat, D. Kanguzhiyev, D. Radev, **G. Balbayev**. FPGA (Field Programmable Gate Array) Technology for Space Communications. *Journal of Engineering Science and Technology Review*. 2020 Special Issue, SI (2020), pp. 54-57.

6. A. Nussubaliyev, A. Mussina, **G. Balbayev**. Artificial Adaptive Filter for Robotic Systems. *Journal of Engineering Science and Technology Review*. 2020 Special Issue, SI (2020), pp. 118-121.